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Resource ALlocation Planning Helper

(RALPH)

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RALPH Background

- Developed to plan Deep Space Network tracking, maintenance, and ground based science
 - o 12 antennas around the world
 - o 30 active users of the DSN
 - o Weekly plans
 - o Approximately 300 "tracks" per week
- Used to generate schedules up to 2 years in advance
- Developed within Design Team approach (close interaction)
- Operational Since 1987
- Under configuration management since 1989

RALPH Schedule Lifecycle

10 years - 2 years Forecasts of resource utilization Forecasts of user contention

Evaluation of mission sets

2 years - 8 weeks Generation of detailed schedules

Review and conflict resolution

Adaptation to changing requirements

8 weeks - real time Implementation of schedules

Reaction to spacecraft emergencies

Reaction to resource outages

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DGW-2

Scheduling Approach

- Two pass scheduling
 - Probablistic look-ahead (profile of resource usage)
 - Schedule using profile as measure of expected conflict
- Generic representation of problem
 - Actual problem described by external files (not code)
 - Three types of resources
 - Static
 - o Variable
 - o Depletable
 - Requirements described in terms of
 - Variable Separations
 - Variable Durations
 - o Configuration dependent pre and post activity times
 - User Windows
 - Triggers (Viewperiods)

Technology Layering

Applications Level

- DSN (RALPH)
- Space Station Assembly Sequence (FAST)
- Space Station Operations Scheduling Simulation (TOMAS)
- TDRSS Scheduling Prototype

Toolkit Level

- Scheduling
- Resource Look-ahead Profiling
- Interval Algebra
- Conversion routines

Foundation Level - Tree Manipulation Base Routines (TMBR)

- Written in C (fielded on both extended-PC and VAX)
- String storage management
- Dynamic tree manipulation (prune, graft, qualify, etc.)

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DGW-4

Details

- Approximately 30,000 lines of C code (including TMBR)
- 5 30 minutes to generate one week schedule (MicroVAX II)
- Full Environment
 - Form-based requirements entry
 - o Graphics (GKS) and text-based (Curses) schedule editors
 - Listings
 - Plots
 - Import and export facilities
 - Multi-user system

RALPH Directions

- Migrate towards more iterative rescheduling capability
- C++ version in the works
- Change operational platform to network environment
- Expand representational base
- Continue to expand base of applications

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DGW-6

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